

# Finite and Infinite Calculus & Infinite Sums

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# Overview

Mathematicians have developed a “finite calculus” analogous to the more traditional infinite calculus, by which it is possible to approach summation in a nice, systematic fashion.

Infinite calculus is based on the properties of the **derivative operator**  $D$ , defined by

$$Df(x) = \lim_{h \rightarrow 0} \frac{f(x+h) - f(x)}{h}.$$

Finite calculus is based on the properties of the **difference operator**  $\Delta$ , defined by

$$\Delta f(x) = f(x+1) - f(x).$$

The symbols  $D$  and  $\Delta$  are called **operators** because they operate on functions to give new functions ; they are functions of functions that produce functions.

Let  $f(x) = x^m$ . Then  $Df(x) = mx^{m-1}$ . But  $\Delta$  does not produce an equally elegant result. For example,

$$\Delta(x^3) = 3x^2 + 3x + 1 \neq 3x^2.$$

But there is a type of “ $m$ th power” that does transform nicely under  $\Delta$ , and this is what makes finite calculus interesting. Such  **$m$ th powers (factorial functions)** are defined by the rule

$$x^{\underline{m}} = x(x-1)\cdots(x-m+1), \quad \text{for } m \geq 0.$$

There is also a corresponding definitions where the factors go up and up:

$$x^{\overline{m}} = x(x+1)\cdots(x+m-1), \quad \text{for } m \geq 0.$$

When  $m = 0$ , we have  $x^{\underline{0}} = x^{\overline{0}} = 1$ , because a product of no factors is **conventionally taken** to be 1 (just as a sum of no terms is conventionally 0.)

The quantity  $x^{\overline{m}}$  is called “ $x$  to the  $m$  falling”, similarly,  $x^{\underline{m}}$  is “ $x$  to the  $m$  rising”.

These functions are also called **falling factorial powers** or rising factorial powers, since they are closely related to the factorial function

$$n! = n(n-1)\cdots 1.$$

In fact,

$$n! = n^{\underline{n}} = 1^{\overline{n}}.$$

We defined  $x^{\overline{m}}$  for  $m \geq 0$ .

To get from  $x^{\overline{3}}$  to  $x^{\overline{2}}$ , we divide by  $x - 2$ . That is,  $x^{\overline{2}} = \frac{x^{\overline{3}}}{x-2}$ .

To get from  $x^{\overline{2}}$  to  $x^{\overline{1}}$ , we divide by  $x - 1$ . That is,  $x^{\overline{1}} = \frac{x^{\overline{2}}}{x-1}$ .

To get from  $x^{\overline{1}}$  to  $x^{\overline{0}}$ , we divide by  $x$ . That is,  $x^{\overline{0}} = \frac{x^{\overline{1}}}{x}$ .

To go from  $x^0$  to  $x^{-1}$ , we should divide by  $x + 1$ . Hence  $x^{-1} = \frac{x^0}{x+1}$ .

Similarly,  $x^{-m} = \frac{1}{(x+1)(x+2)\cdots(x+m)}$  for  $m > 0$ .

We shall later define falling powers for real or even complex number  $m$ .

## Exercise

1. Prove that the formula  $x^{m+n} = x^m(x - m)^n$  (falling power version) for falling powers (analogous to the law of exponents,  $x^{m+n} = x^m + x^n$  for ordinary powers).

Let  $m$  be an integer. Verify that

$$\Delta x^m = mx^{m-1} \quad \text{when } m < 0.$$

Falling powers  $x^m$  are especially nice with respect to  $\Delta$ .

$$\Delta(x^m) = mx^{m-1},$$

hence the finite calculus has a handy law to match  $D(x^m) = mx^{m-1}$ .

The operator  $D$  of infinite calculus has an inverse, the anti-derivative (or integration) operator  $\int$ . The **Fundamental Theorem of Calculus** relates  $D$  to  $\int$  :

$$g(x) = Df(x) \iff \int g(x)dx = f(x) + c.$$

Here  $\int g(x)dx$ , the **indefinite integral** of  $g(x)$ , is the class of functions whose derivative is  $g(x)$  and  $c$  for “indefinite integrals” is an arbitrary constant.

Analogously,  $\Delta$  has an inverse, the **anti-difference** (or **summation**) **operator**  $\sum$  ; and there is another fundamental theorem :

$$g(x) = \Delta f(x) \iff \sum g(x)\delta x = f(x) + c.$$

Here  $\sum g(x)\delta x$ , the **indefinite sum** of  $g(x)$ , is the class of functions whose difference is  $g(x)$  and  $c$  for “indefinite sums” is an arbitrary function  $p(x)$  such that  $p(x+1) = p(x)$ .

## Exercise

2. Find  $\Delta f(x)$ , where  $f(x)$  is the periodic function  $a + b \sin 2\pi x$ .

Infinite calculus has definite integrals: If  $g(x) = Df(x)$ , then

$$\int_a^b g(x) dx = f(x) \Big|_a^b = f(b) - f(a).$$

Finite calculus has definite sums: If  $g(x) = \Delta f(x)$ , then

$$\sum_a^b g(x) \delta x = f(x) \Big|_a^b = f(b) - f(a).$$

Assume that  $g(x) = \Delta f(x) = f(x+1) - f(x)$ .

### Special cases:

- If  $a = b$ , we have  $\sum_a^b g(x)\delta x = f(b) - f(a) = 0$ .
- Next, if  $b = a + 1$ , the result is

$$\sum_a^{a+1} g(x)\delta x = f(a+1) - f(a) = g(a).$$

- More generally, if  $b$  increases by 1, we have the difference

$$\begin{aligned} \sum_a^{b+1} g(x)\delta x - \sum_a^b g(x)\delta x &= [f(b+1) - f(a)] - [f(b) - f(a)] \\ &= f(b+1) - f(b) = g(b). \end{aligned}$$



- When  $a$  and  $b$  are integers with  $b \geq a$ ,

$$\sum_a^b g(x)\delta x = \sum_{k=0}^{b-1} g(k) = \sum_{a \leq k < b} g(k).$$

In other words, the definite sums is the same as an ordinary sum with limits, but excluding the value at the upper limit.

- What happens when  $b < a$ ?

$$\sum_a^b g(x)\delta x f(b) - f(a) = -(f(a) - f(b)) = -\sum_a^b g(x)\delta x.$$

- For any integers  $a, b, c$

$$\sum_a^b g(x)\delta x + \sum_b^c g(x)\delta x = \sum_a^c g(x)\delta x.$$

Suppose we want to find the sum of the form

$$\sum_{a \leq k < b} g(k) = \sum_a^b g(x) \delta x.$$

If we are able to find an **anti-difference** function  $f$  such that

$$g(x) = f(x + 1) - f(x),$$

then

$$\begin{aligned} \sum_{a \leq k < b} g(k) &= \sum_{a \leq k < b} f(x + 1) - f(x) \quad (\text{telescoping series}) \\ &= [f(a + 1) - f(a)] + [f(a + 2) - f(a + 1)] + \cdots + [f(b) - f(b - 1)] \\ &= f(b) - f(a). \end{aligned}$$

We shall see that definite summation gives us a simple way to compute sums of falling powers.

Ordinary powers can also be summed in new way, if we express them in terms of falling powers. For example,

$$k^2 = k^{\underline{2}} + k^{\underline{1}}$$

hence

$$\sum_{0 \leq k < n} k^2 = \frac{k^{\underline{3}}}{3} + \frac{k^{\underline{2}}}{2} \Big|_{k=0}^{k=n} = \frac{1}{3} n \left( n - \frac{1}{2} \right) (n - 1).$$

Replacing  $n$  by  $n + 1$  gives us yet another way to compute the value of

$$\square_n = \sum_{0 \leq k \leq n} k^2$$

in closed form.

It is always possible to convert between ordinary powers and factorial powers by using Stirling numbers, which will be later studied.

Falling powers are very nice for sums.

## Exercises

3. Prove that  $(x + y)^2 = x^2 + 2x^1y^1 + y^2$ .
4. State and prove that the factorial binomial theorem.
5. Prove that the summation property  $\sum_a^b x^m \delta x = \frac{x^{m+1}}{m+1} \Big|_a^b$  holds for any integer  $m \neq -1$  and any  $x$ .
6. Does the summation property hold for  $m = -1$ ?

Recall that for integration we use

$$\int_a^b x^{-1} dx = \log x \Big|_a^b$$

when  $m = -1$ .

What is a finite analog of  $\log x$ ?

What is the function  $f(x)$  satisfying

$$x^1 = \frac{1}{x+1} = \Delta f(x) = f(x+1) - f(x).$$

Hence  $f(x)$  is the harmonic number

$$H_x = 1 + \frac{1}{2} + \cdots + \frac{1}{x}.$$

Thus  $H_x$  is the discrete analog of the continuous  $\log x$ .

We shall define  $H_x$  for noninteger  $x$  and for large values of  $x$ , the value of  $H_x - \log x$  is approximately

$$0.577 + \frac{1}{2x}.$$

Hence  $H_x$  and  $\log x$  are not only analogous, their values usually differ by less than 1.

We can now give a complete description of the sums of falling powers:

$$\sum_a^b x^m \delta x = \frac{x^{m+1}}{m+1} \Big|_a^b \quad \text{if } m \neq -1$$

$$H_x \Big|_b^a \quad \text{if } m = -1.$$

This formula indicates why harmonic numbers tend to pop up in the solutions to discrete problems like the analysis of quicksort, just as so-called natural logarithms arise naturally in the solutions to continuous problems.

## Exercise

7. Prove that  $2^x$  is the discrete analog for  $e^x$ , called the discrete exponential function.

Despite all the parallels between continuous and discrete math, some continuous notions have no discrete analog.

For example, the **chain rule** for the derivative of a function of a function ; but there is no corresponding chain rule of finite calculus, because there is no nice form for  $\Delta f(g(x))$ .

Discrete change-of-variables is hard, except in certain cases like the replacement of  $x$  by  $c \pm x$ .

However,  $\Delta(f(x)g(x))$  does have a fairly nice form, and it provides us with a rule for **summation by parts**, the finite analog of what infinite calculus calls integration by parts.

Let us recall the formula

$$D(uv) = uDv + vDu$$

of infinite calculus leads to the rule for integration by parts,

$$\int uDv = uv - \int vDu,$$

after integration and rearranging terms; we can do a similar thing in finite calculus.

We start by applying the difference operator to the product of two functions  $u(x)$  and  $v(x)$ :

$$\begin{aligned}\Delta(u(x)v(x)) &= u(x+1)v(x+1) - u(x)v(x) \\ &= u(x+1)v(x+1) - u(x)v(x+1) + u(x)v(x+1) - u(x)v(x) \\ &= u(x)\Delta v(x) + v(x+1) + v(x+1)\Delta u(x).\end{aligned}$$



This formula can be put into a convenient form using the **shift operator**  $E$ , defined by

$$Ef(x) = f(x + 1).$$

Hence  $\Delta(uv) = u\Delta v + Ev\Delta u$ .

Taking the indefinite sum on both sides of this equation, and rearranging its terms, yields the rule for summation by parts:

$$\sum u\Delta v = uv - \sum Ev\Delta u.$$

This rule is useful when the sum on the left is harder to evaluate than the one on the right.

## Exercise

8. Find the sum of the following :

•  $\sum_{k=0}^n k2^k$

•  $\sum_{0 \leq k < n} kH_k.$

# Infinite Sums

- The methods we have used for manipulating  $\sum$ 's are **not** always valid when infinite sums are involved.
- There is a large, easily understood class of infinite sums for which all the operations we have been performing are perfectly legitimate.

Suppose all the terms  $a_k$  are non-negative. If there is a **bounding constant**  $A$  such that

$$\sum_{k \in F} a_k \leq A$$

for all finite subsets  $F$  of  $K$ , then we define  $\sum_{k \in K}$  to be the least such  $A$ .

It follows from a well-known properties of the real numbers that the set of all such  $A$  always contains a smallest element.

The definition has been formulated carefully so that it doesn't depend on any order that might exist in the index set  $K$

But there is **no bounding constant**  $A$ , we say that

$$\sum_{k \in K} a_k = \infty.$$

If  $K$  is the set of non-negative integers, then for non-negative terms  $a_k$ , we

have 
$$\sum_{k \geq 0} a_k = \lim_{n \rightarrow \infty} \sum_{k=0}^n a_k.$$

- $\sum_{k \geq 0} x^k$  can be calculated as follows:

$$\sum_{k \geq 0} x^k = \lim_{n \rightarrow \infty} \frac{1 - x^{n+1}}{1 - x} = \begin{cases} \frac{1}{1-x} & \text{if } 0 \leq x < 1 \\ \infty & \text{if } x \geq 1. \end{cases}$$

- $$\sum_{k \geq 0} \frac{1}{(k+1)(k+2)} = \lim_{n \rightarrow \infty} \sum_{k=0}^n k^{-2} = \lim_{n \rightarrow \infty} \left. \frac{k^{-1}}{-1} \right|_0^n = 1.$$

- There is something **flaky** about a sum that gives different values when its terms are added up in different ways.

- How to find  $\sum_{k \in K} a_k$ , where  $a_k$  is a real-valued term defined for each  $k \in K$ ?

- Any real number  $x$  can be written as the difference of its positive and negative parts,  $x = x^+ - x^-$ , where  $x^+ = x.[x > 0]$  and  $x^- = -x.[x < 0]$ . Because  $a_k^+$  and  $a_k^-$  are non-negative, we can find value for the infinite sums  $\sum_{k \in K} a_k^+$  and  $\sum_{k \in K} a_k^-$ .

Hence  $\sum_{k \in K} a_k = \sum_{k \in K} a_k^+ - \sum_{k \in K} a_k^-$  unless the right-hand sums are both equal to  $\infty$ .

Let  $A^+ = \sum_{k \in K} a_k^+$  and  $A^- = \sum_{k \in K} a_k^-$ .

- If  $A^+$  and  $A^-$  are both finite, the sum  $\sum_{k \in K} a_k$  is said to **converge absolutely** to the value  $A = A^+ - A^-$ .
- If  $A^+ = \infty$  but  $A^-$  is finite, the sum  $\sum_{k \in K} a_k$  is said to **diverge** to  $+\infty$ .
- If  $A^- = \infty$  but  $A^+$  is finite, the sum  $\sum_{k \in K} a_k$  is said to **diverge** to  $-\infty$ .
- If  $A^+ = A^- = \infty$ , we call  $\sum_{k \in K} a_k$  is undefined.

## Exercise

9. We started with a definition that worked for non-negative terms, then we extend it to real-valued terms. Extend the definition if the terms of complex numbers.

All of the manipulations we have done for finite sums are perfectly valid whenever we are dealing with “**sums that converge absolutely**”.

Each of the following transformation rules preserves the value of all absolutely convergent sums.

- distributive law
- commutative law
- associative law
- rule for summing first on one index variable.

Absolutely convergent sums over 2 or more indices can always be summed first with respect to any one of those indices.

# References

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